Novel Magnetic Force Microscopy Operation Employing Torsional Resonance Mode

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Abstract

The constant miniaturization of magnetic bits in hard-disk drives creates the need for a convenient and versatile high resolution magnetic imaging method. Magnetic Force Microscopy (MFM), a scanning probe technique, has been widely used for this purpose for more than two decades [1,2]. However, the current MFM lateral resolution in ambient conditions is roughly equal to the magnetic bit size of commercial hard-disks (\approx 40 nm), making imperative the improvement of MFM performance. In this work, we present the advantages of performing MFM imaging employing the Torsional Resonance (TR) mode of cantilever oscillation [3].

Traditional vibrating tip modes of MFM operation, e.g. Tapping Mode MFM (TM-MFM), employ the flexural ("diving board") cantilever deflection signal for feedback control, while the detection scheme is principally sensitive to forces perpendicular to the sample. However, TR-MFM takes advantage of the torsional (twisting) cantilever deflection. In this case, lateral forces that act on the tip can cause a change in the torsional resonance frequency of the cantilever, allowing the local characterization of sample properties and the detection of in-plane components of force-fields.

The utilization of TR mode for imaging in-plane components of magnetic fields has been demonstrated [4,5], but not extensively studied. In this work, TR-MFM is examined in detail [6]. Measurements have been performed using a commercial scanning probe microscope (Dimension Icon, Bruker). Home-coated magnetic probes have been used: hard magnetic CoCr layers have been deposited on commercial Atomic Force Microscopy (AFM) probes (Nanosensors), using ultrahigh vacuum magnetron sputtering. A double-pass method is used for performing MFM measurements: a TM-AFM main scan yields the surface topography, while the long-range magnetic forces are detected using a lifted TR-MFM scan (or a TM-MFM scan, for comparison).

TR-MFM provides two main advantages over conventional TM-MFM measurements. The first is related to the insensitivity of TR mode to out-of-plane forces and most notably, the Van der Waals forces. Thus, the only long-range forces contributing to the signal detection scheme are magnetic forces, allowing the magnetic imaging of a surface with total absence of topography-related signal (see figure 1). The second advantage originates from the minimal flexural oscillation amplitude. As the flexural cantilever oscillation is only excited thermally, the corresponding oscillation amplitude is around 1 nm, more than one order of magnitude lower than in the case of TM-MFM. This provides the ability of performing dynamic MFM measurements with significantly reduced tip sample distance (the tip can even be lowered during the "lifted" scan). As a result, improved spatial resolution can be achieved (see figure 2), while preserving a high signal-to-noise ratio.

Taking into account the above-mentioned advantages, it is argued that TR-MFM provides a significant improvement to a prolific magnetic imaging method widely used in Academia and in Industry.

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Figure 1: MFM phase imaging of a 0.1 Gb/inch² longitudinal magnetization hard-disk. The images have been obtained at the same position. (a-c) TM-MFM, lift height: 20 nm, (a) topography (0 – 68.4 nm), (b) phase image (0 – 4.3 deg.), signal/noise ratio: 13, (c) derivative of phase image (0 – 10.6 deg/µm). (d-f) TR-MFM, same area as in (a-c), lift height: -5 nm, (a) topography (0 – 60.0 nm), (b) phase image (0 – 0.5 deg.), signal/noise ratio: 25 (c) derivative of phase image (0 – 2.4 deg/µm). As TR mode is sensitive to lateral force gradients, the TR-MFM contrast is reversed with respect to TM-MFM.



Figure 2: MFM phase imaging of a 100 Gb/inch2 perpendicular magnetization hard-disk. The images have been obtained at the same position. (a) TM-MFM phase image, lift height: 15 nm, color scale: 0 – 2.4 deg., S/N ratio: 17. (b) TR-MFM phase image, same area as in (a), lift height: -29 nm, color scale: 0 – 1.0 deg., S/N ratio: 4. (c) Line profiles averaged along the indicated directions in (a) and (b). The TM-MFM line profile has been inverted.